

Autonics

ROTARY ENCODER(INCREMENTAL TYPE)

E20 SERIES

INSTRUCTION MANUAL



Thank you for choosing our Autonics product.
Please read the following safety considerations before use.

Safety Considerations

⚠ Please observe all safety considerations for safe and proper product operation to avoid hazards.
⚠ symbol represents caution due to special circumstances in which hazards may occur.

- Warning** Failure to follow these instructions may result in serious injury or death.
- Caution** Failure to follow these instructions may result in personal injury or product damage.

Warning

- Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss.** (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.)
Failure to follow this instruction may result in fire, personal injury, or economic loss.
- Install on a device panel to use.**
Failure to follow this instruction may result in fire.
- Do not connect, repair, or inspect the unit while connected to a power source.**
Failure to follow this instruction may result in fire.
- Check 'Connections' before wiring.**
Failure to follow this instruction may result in fire.
- Do not disassemble or modify the unit.**
Failure to follow this instruction may result in fire.

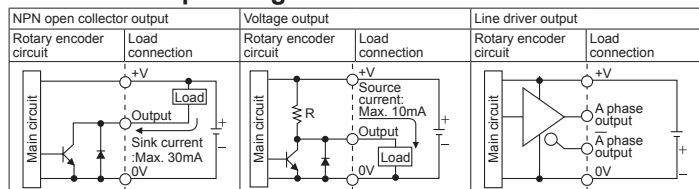
Caution

- Use the unit within the rated specifications.**
Failure to follow this instruction may result in fire or product damage.
- Do not short the load.**
Failure to follow this instruction may result in product damage by fire.
- Do not use the unit in the place where flammable/explosive/corrosive gas, humidity, direct sunlight, radiant heat, vibration, impact, or salinity may be present.**
Failure to follow this instruction may result in fire or explosion.
- Do not use the unit near the place where there is the equipment which generates strong magnetic force or high frequency noise and strong alkaline, strong acidic exists.**
Failure to follow this instruction may result in product damage.

Ordering Information

E20(S)	2	360	3	N	12	R
Series	Shaft diameter	Pulses/Revolution	Output phase	Output type	Power supply	Cable
E20S Diameter Ø20mm, Shaft type	Ø2mm	100, 200, 320,	3: A, B, Z 6: A, B, Z A, B, Z	N: NPN open collector output V: Voltage output L: Line driver output	5 : 5VDC±5% 12 : 12VDC±5%	R : Axial cable type S : Radial cable type
E20HB Diameter Ø20mm, Built-in type	Ø2mm, Ø2.5mm, Ø3mm	360		⚠ The power of Line driver is only for 5VDC.		

Control Output Diagram



- The output circuit of A, B, Z phase are the same. (Line driver output is A, A, B, B, Z, Z)

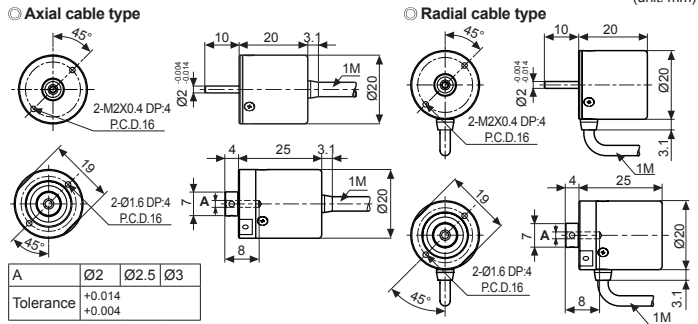
⚠ The above specifications are subject to change and some models may be discontinued without notice.
⚠ Be sure to follow cautions written in the instruction manual, and the technical descriptions (catalog, homepage).

Specifications

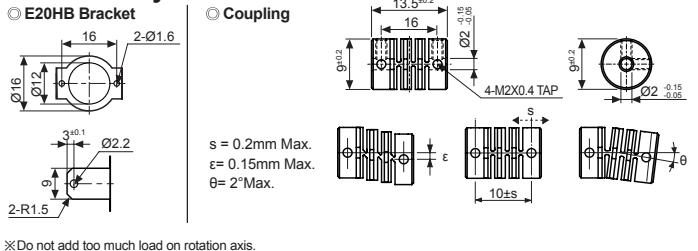
Item	Ø20mm Shaft type Incremental Rotary Encoder	Ø20mm Built-in type Incremental Rotary Encoder
Model	E20S2-3-N-□□ E20S2-3-V-□□ E20S2-6-L-5□	E20HB-3-N-□□ E20HB-3-V-□□ E20HB-6-L-5□
Resolution(PPR)	100, 200, 320, 360 (Not indicated pulse and output type is customizable.)	
Output phase	A, B, Z phase (Line driver output A, A, B, B, Z, Z phase)	
Phase difference of output	Phase difference between A and B: $T \pm \frac{T}{4} \pm \frac{T}{8}$ (T=1 cycle of A phase)	
Electrical specification	NPN open collector output	Load current : Max. 30mA, Residual voltage : Max. 0.4VDC=
	Voltage output	Load current : Max. 10mA, Residual voltage : Max. 0.4VDC=
	Line driver output	• Low - Load current: Max. 20mA, Residual: Max. 0.5VDC= • High - Load current: Max. -20mA, Output voltage: Min. 2.5VDC=
	Response time (Rise/Fall)	Max. 1µs
Line driver output	Max. 1µs	
Line driver output	Max. 0.5µs	
Max. Response frequency	100kHz	
Power supply	• 5VDC= ±5% • 12VDC= ±5%	
Current consumption	Max. 60mA(disconnection of the load), Line driver output:Max. 50mA(disconnection of the load)	
Insulation resistance	Min. 100MΩ(at 500VDC between all terminals and case)	
Dielectric strength	500VAC 50/60Hz for 1 minute(Between all terminals and case)	
Connection	Axial cable type, Radial cable type	
Mechanical specification	Starting torque	Max. 5gf·cm(5×10 ⁻⁴ N·m)
	Moment of inertia	Max. 0.5g·cm ² (5×10 ⁻⁶ kg·m ²)
	Shaft loading	Radial: 200gf, Thrust : 200gf
	Max. allowable revolution ^{*1}	6000rpm
Vibration	1.5mm amplitude at frequency of 10 to 55Hz in each of X, Y, Z directions for 2 hours	
Shock	Max. 50G	
Environ	Ambient temperature	-10 to 70°C(at non-freezing status), Storage : -20 to 80°C
-ment	Ambient humidity	35 to 85%RH, Storage : 35 to 90%RH
Protection	IP50(IEC standard)	
Cable	Ø3mm, 5P(Line driver output : 8P), Length:1m, Shield cable	
Accessory	Ø2mm Coupling(Shaft type), Bracket(Built-in type)	
Approval	CE (Except Line driver output)	
Unit weight	Approx. 35g	

⚠ 1: Max. allowable revolution Max. response revolution
 【Max. response revolution(rpm)= $\frac{\text{Max. response frequency} \times 60}{\text{Resolution}} \text{ sec}$ 】
 Please select the resolution to make lower max. revolution than max. allowable revolution.

Dimension

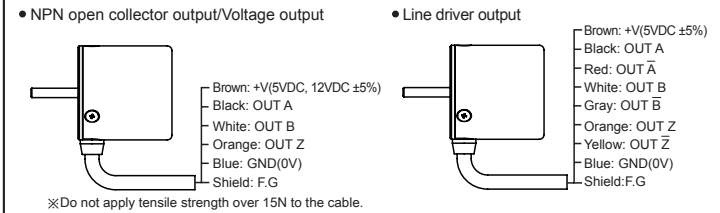


Accessory

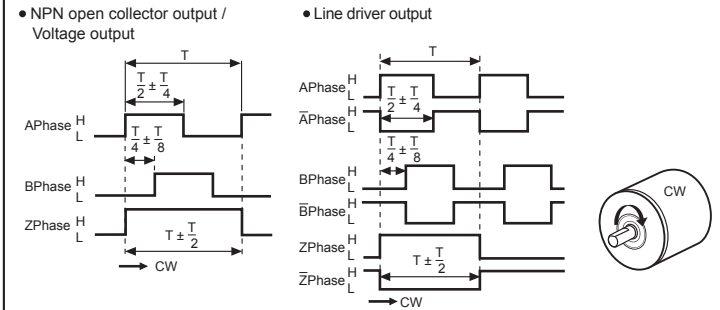


⚠ Do not add too much load on rotation axis.
 ⚠ Do not put strong impact when insert a coupling into shaft.
 Failure to follow this instruction may result in product damage.
 ⚠ Fix the unit or a coupling by a wrench under 0.15 N·m of torque.
 ⚠ When you install this unit, if eccentricity and deflection angle are larger, it may shorten the life cycle of this unit.

Connections



Output Waveform



Cautions during Use

- Follow instructions in 'Cautions during Use'. Otherwise, It may cause unexpected accidents.
- 5VDC, 12VDC power supply should be insulated and limited voltage/current or Class 2, SELV power supply device.
- For using the unit with the equipment which generates noise (switching regulator, inverter, servo motor, etc.), ground the shield wire to the F.G. terminal.
- Ground the shield wire to the F.G. terminal.
- When using switching mode power supply, frame ground (F.G.) terminal of power supply should be grounded.
- Wire as short as possible and keep away from high voltage lines or power lines, to prevent inductive noise.
- For Line driver unit, use the twisted pair wire which is attached seal and use the receiver for RS-422A communication.
- Check the wire type and response frequency when extending wire because of distortion of waveform or residual voltage increment etc by line resistance or capacity between lines.
- This unit may be used in the following environments.
 - ① Indoors (in the environment condition rated in 'Specifications')
 - ② Altitude max. 2,000m
 - ③ Pollution degree 2
 - ④ Installation category II

Major Products

- Photoelectric Sensors
- Fiber Optic Sensors
- Door Sensors
- Door Side Sensors
- Area Sensors
- Proximity Sensors
- Pressure Sensors
- Rotary Encoders
- Connector/sockets
- Switching Mode Power Supplies
- Control Switches/Lamps/Buzzers
- I/O Terminal Blocks & Cables
- Stepper Motors/Drivers/Motion Controllers
- Graphic/Logic Panels
- Field Network Devices
- Laser Marking System (Fiber, CO₂, Nd: YAG)
- Laser Welding/Cutting System
- Temperature Controllers
- Temperature/Humidity Transducers
- SSRs/Power Controllers
- Counters
- Timers
- Panel Meters
- Tachometer/Pulse (Rate) Meters
- Display Units
- Sensor Controllers

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